



# The Link Between Ejected Stars, Hardening and Eccentricity Growth of Super Massive Black Holes in Galactic Nuclei

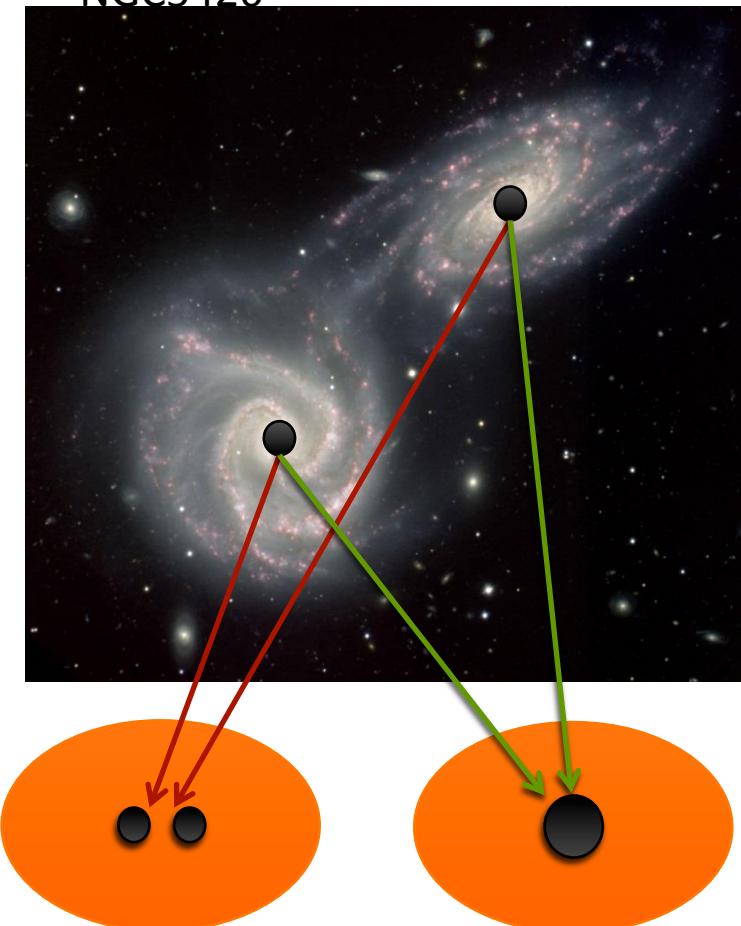
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# Galaxy Mergers

NGC5426

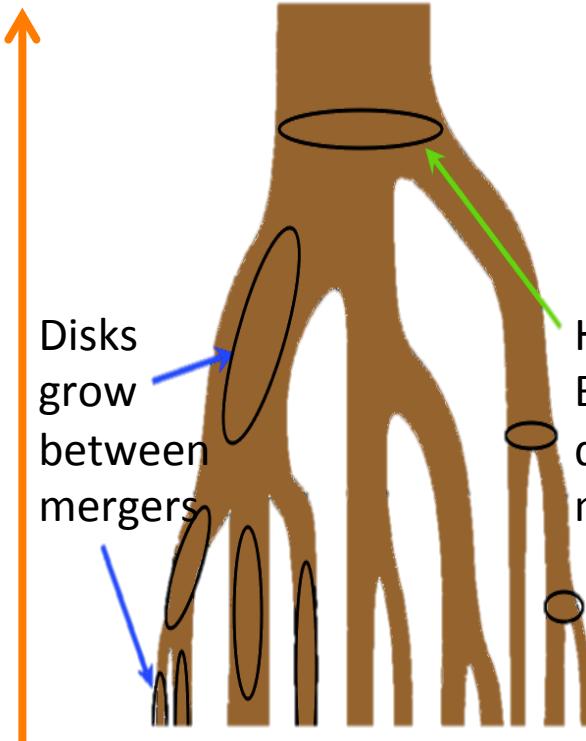


Time

Merger Tree

Disks  
grow  
between  
mergers

Halos &  
Bulges grow  
during  
mergers



# Three Phases Evolution

➤ Three Phases (Begelman et al. 1980).

➤ Dynamical friction (Merritt 2001; Yu 2002)

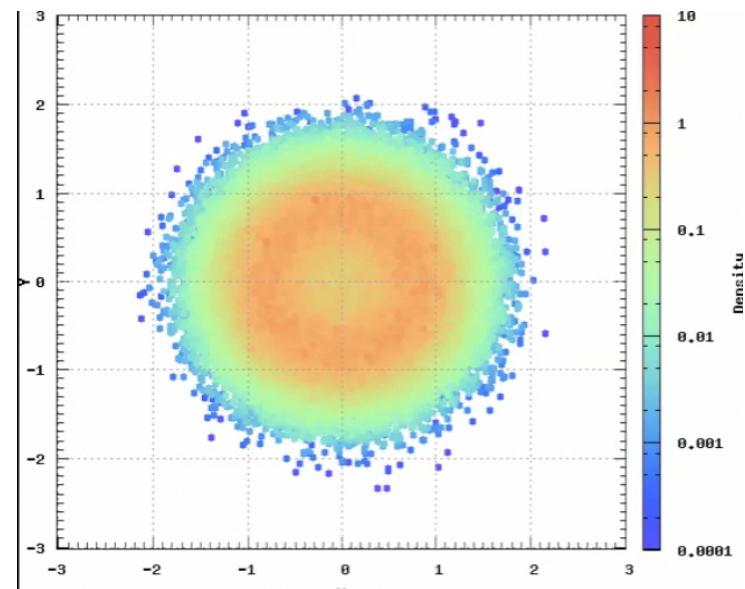
$$t_{df} \sim \frac{4 \times 10^6}{\log N} \left( \frac{\sigma_*}{200 \text{ km/s}} \right) \left( \frac{r_*}{100 \text{ pc}} \right)^2 \left( \frac{10^8 M_{\text{sun}}}{m_{BH}} \right) \text{ yr}$$

➤ Three body interactions (Quinlan 1996)

➤ Gravitational Waves Radiation (Peters 1964)

$$a_h \approx G \mu / 4 \sigma_*^2 \approx 10^{-3} - 0.1 \text{ pc}$$

$$t_{\text{merge}} \sim \frac{3}{85} \frac{c^5 a^4}{G^3 \mu M_{BH1,2}^2} (1 - e^2)^{7/2} \sim 10^7 \left( \frac{a}{0.01 \text{ pc}} \right)^4 \left( \frac{10^8 M_{\text{sun}}}{m_{BH1}} \right)^3 (1 - e^2)^{7/2} \frac{m_{BH1}^2}{m_{BH2} M_{BH1,2}} \text{ yr}$$



# Final Parsec Problem

- ↗ Low efficient three body interaction
  - ↗ In merger of gas-poor galaxies
  - ↗ Spherical stellar environment
- ↗ Solution:
  - ↗ Axisymmetry(rotation) & triaxiality of galactic nuclei
    - ↗ (Yu 2002; Merritt & Poon 2004; Berczik et al. 2006; Preto et al. 2011; Fiestas et al. 2012; Gualandris & Merritt 2012; Khan et al. 2012b, 2013)
  - ↗ High initial eccentricity of Massive black hole binary (MBHB)
    - ↗ (Aarseth 2003; Berentzen et al. 2008, 2009a; Preto et al. 2009, 2011; Khan et al. 2011; Li et al. 2012)
    - ↗ Co-rotating and counter-rotating stars around MBHB (Zier & Biermann 2001, 2002; Iwasawa et al. 2011; Sesana et al. 2011; Meiron & Laor 2013)

# Ejecting stars in large N-body simulations

- ↗ Ejecting stars carry away energy and angular momentum of MBHB during three body interaction phase.
- ↗ One million N-body simulation of galactic nuclei with MBHB
  - ↗ Phi-GPU code ([Berczik et al. 2011](#)) in laohu (NAOC) & Milkyway (Juelich SC)

- ↗ Rotating King Model ([Einsel et al 1999](#))

- ↗  $f(E, J_z) \sim (e^{\beta E} - 1)e^{-\beta \Omega_0 J_z}$

$$\omega_0 = \sqrt{9 / 4\pi G n_c} \Omega_0 \quad W_0 = -\beta m(\phi - \phi_t)$$

# Initial conditions

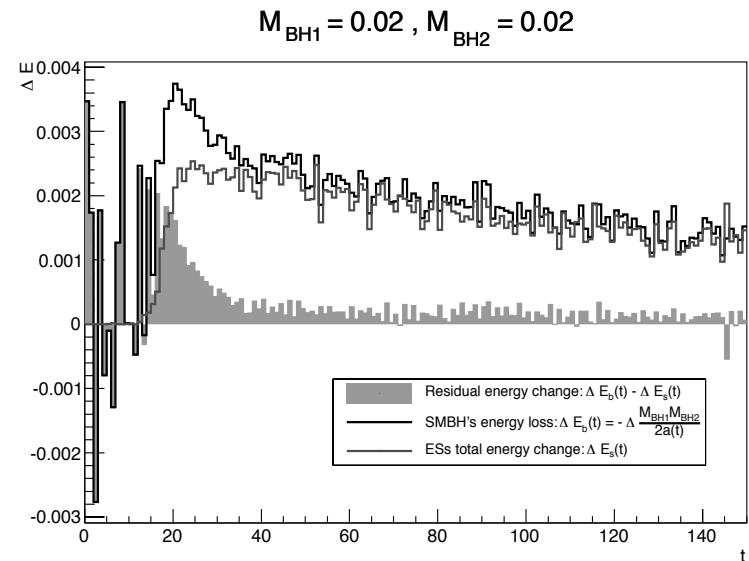
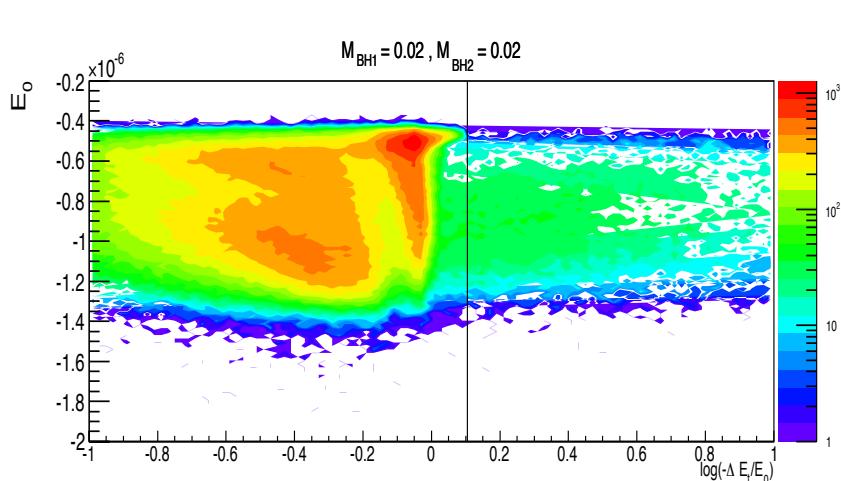
- ↗ King parameters:  $W_0 = 0.6$   $\omega_0 = 1.8 / 0.0$
- ↗ Scaling Free:  $E = -1/4$ ;  $G = 1$ ;  $M_{\text{tot}} = 1$
- ↗ Initial MBHB:  $v_{\text{circ}} = 0.7$ ; separation: 0.6 at the center

Model	0110	0210	0510	1010	2020	4020	4040
$M_{\text{BH}1}$	0.01	0.01	0.01	0.01	0.02	0.04	0.04
$M_{\text{BH}2}$	0.001	0.002	0.005	0.01	0.02	0.02	0.04

- ↗ End time: 150

Example:	$M_{\text{BH}}$	R	T	V
Nbody Unit	0.01	0.6	150	0.7
Astro. Unit	$10^7 M_{\odot}$	600 pc	2.25 Gyr	46 km/s

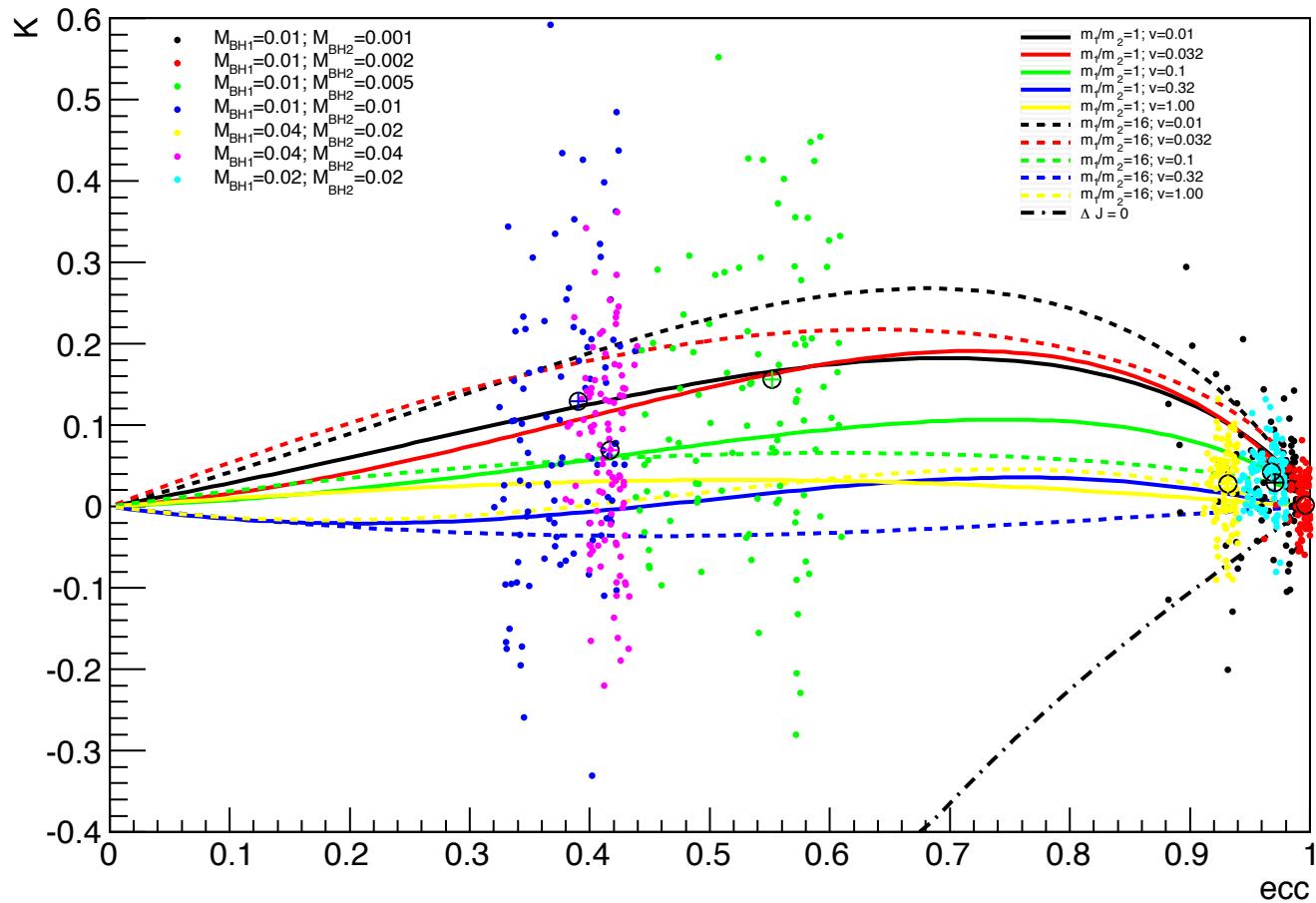
# Ejected star selection



Ejected star samples

Model	0110	0210	0510	1010	2020	4020	4040
$N_{EJ}$	863	3457	10203	16656	40288	57596	83367
$N_{EJ}/N_{TOT}(\%)$	0.086	0.34	1.02	1.67	4.03	5.76	8.34

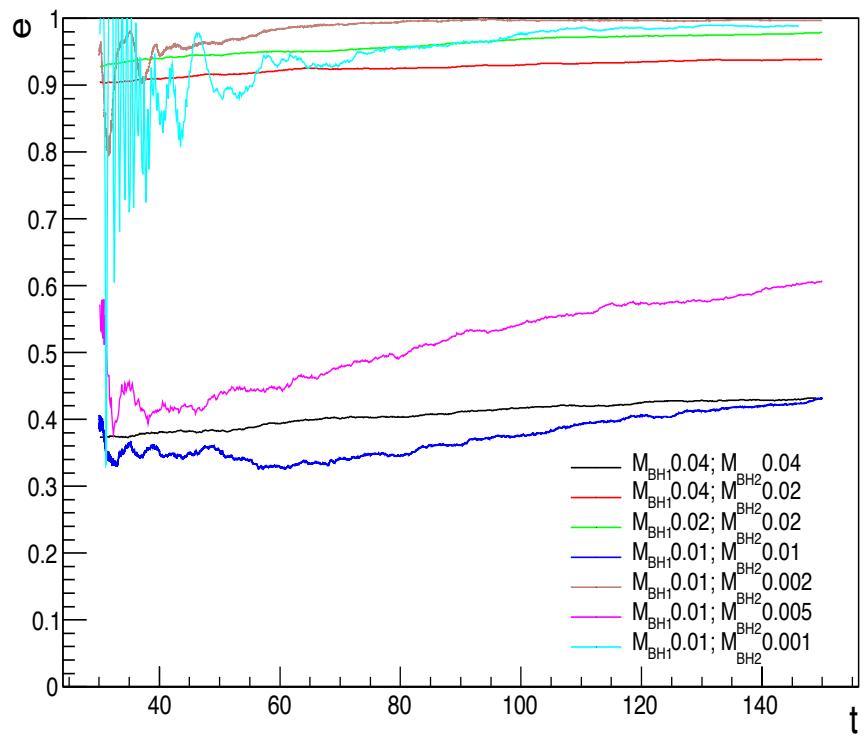
# Results – eccentricity evolution



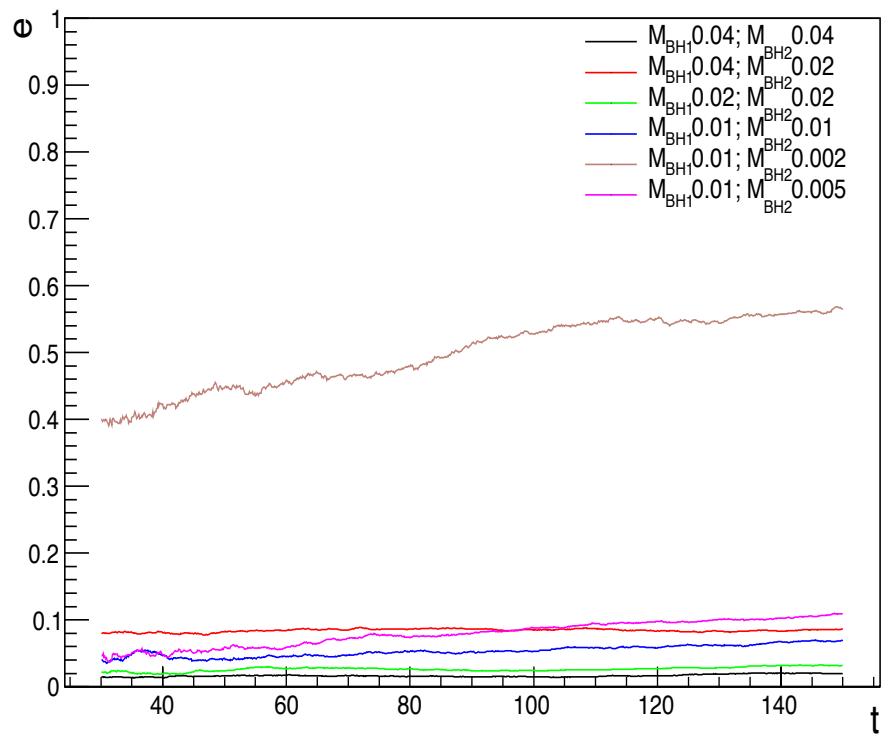
$$K = \frac{\Delta e}{\Delta \ln(1/a)}$$

# Results – eccentricity evolution

Rotating models



Non-rotating models



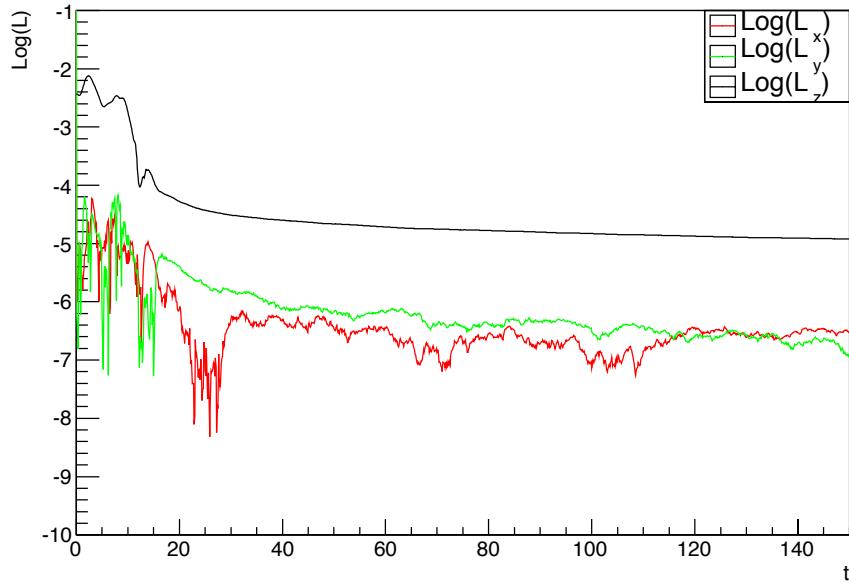
# MBHB angular momentum evolution

$\beta \sim 0^\circ$

Stellar system

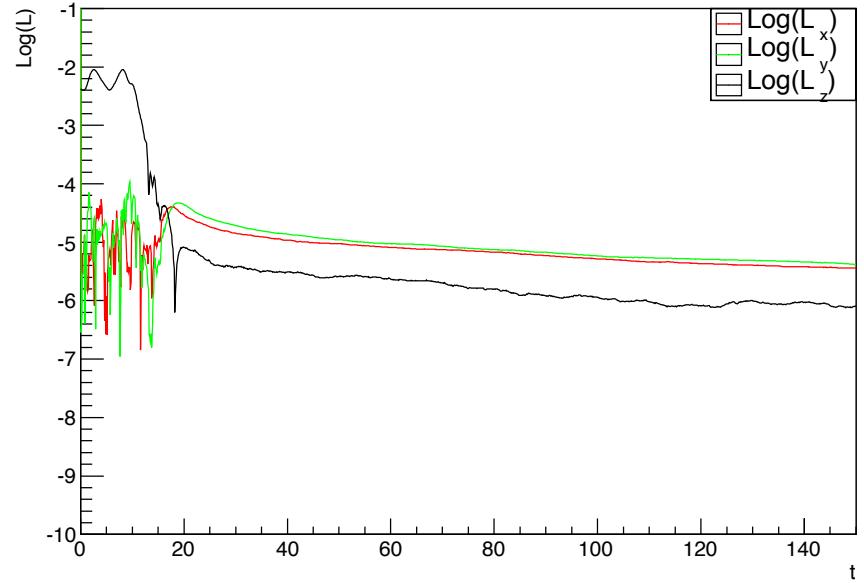


$M_{BH1} = 0.04, M_{BH2} = 0.02$



$\beta \gg 0^\circ$

$M_{BH1} = 0.02, M_{BH2} = 0.02$

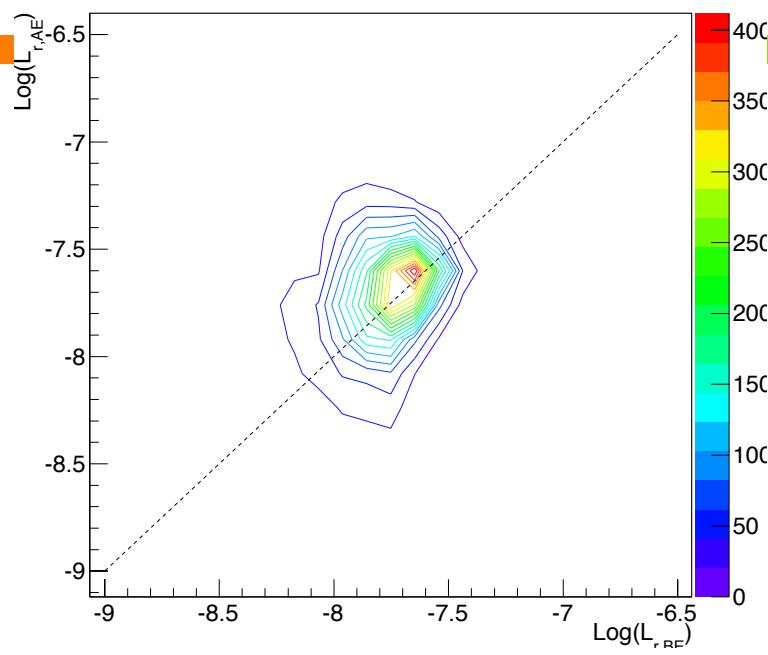


$\beta$ : Inclination angle between MBHB orbit plane and stellar rotating plane

# Ejected star angular momentum change

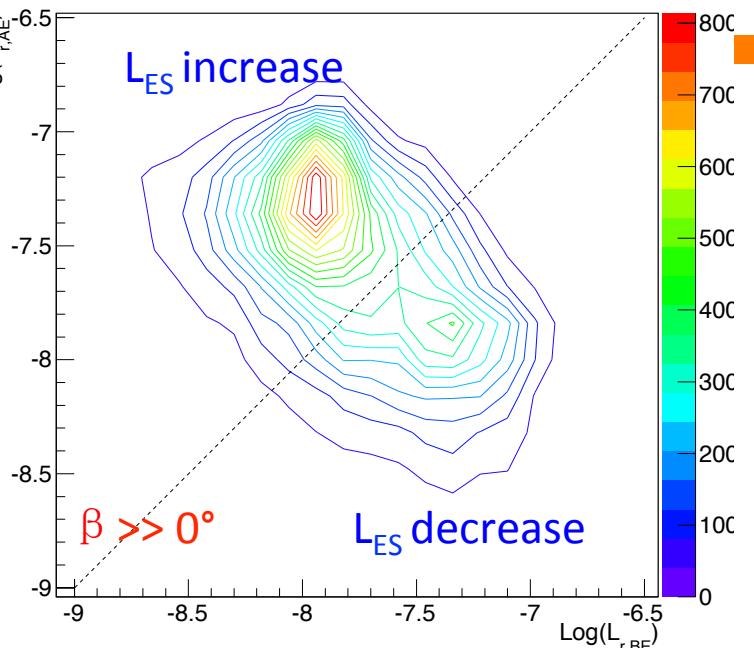
Non-rotating models

$M_{BH1} = 0.02, M_{BH2} = 0.02$

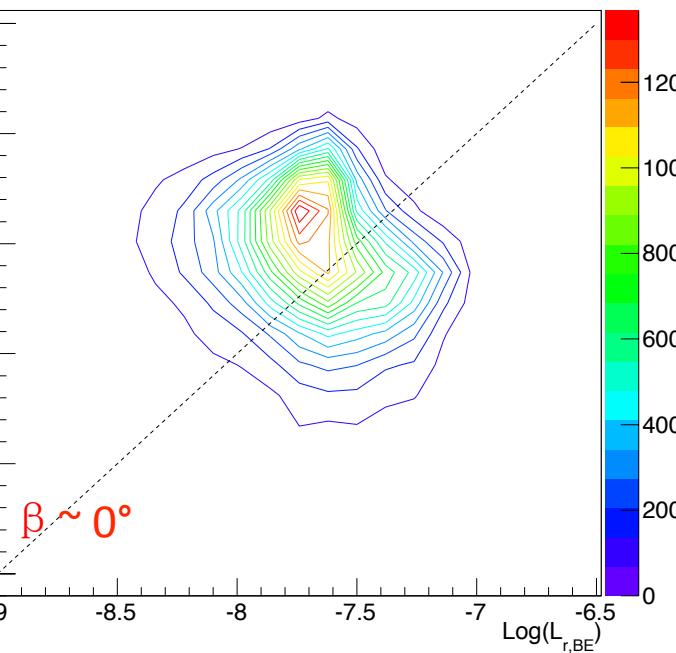
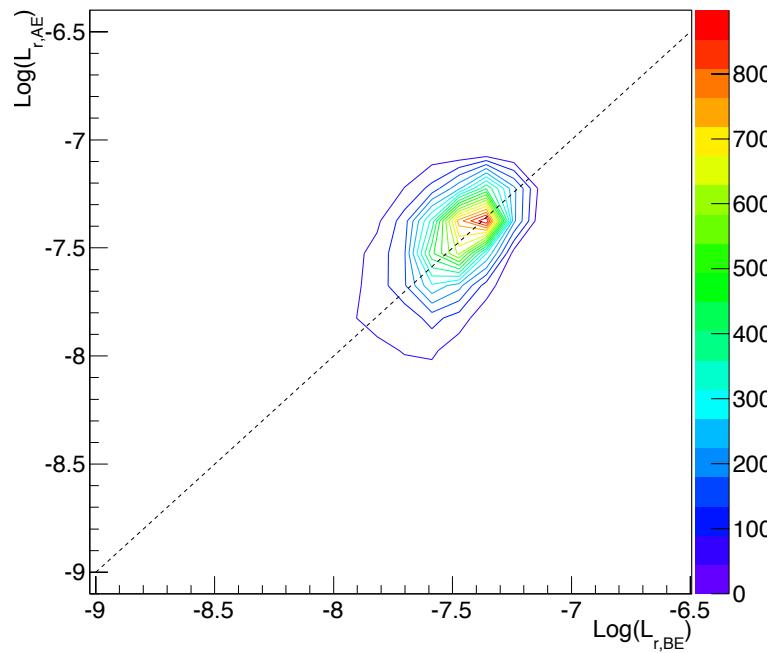


Rotating models

$M_{BH1} = 0.02, M_{BH2} = 0.02$



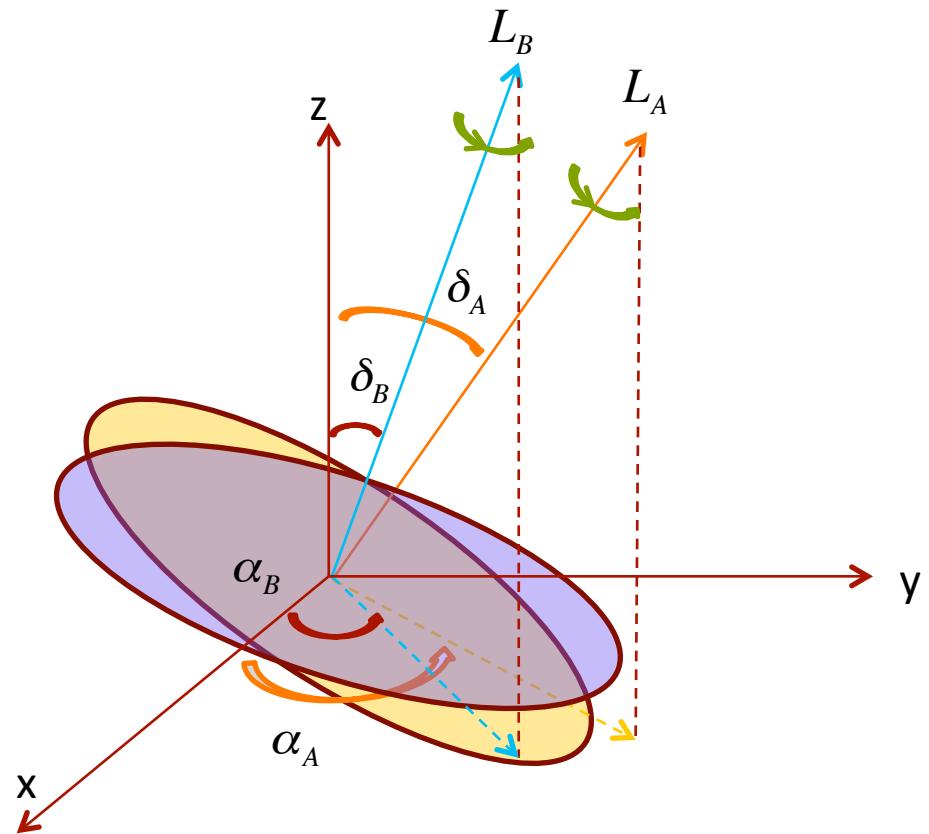
$M_{BH1} = 0.04, M_{BH2} = 0.04$



# Angular momentum angle distribution

## ➤ Spherical coordinate

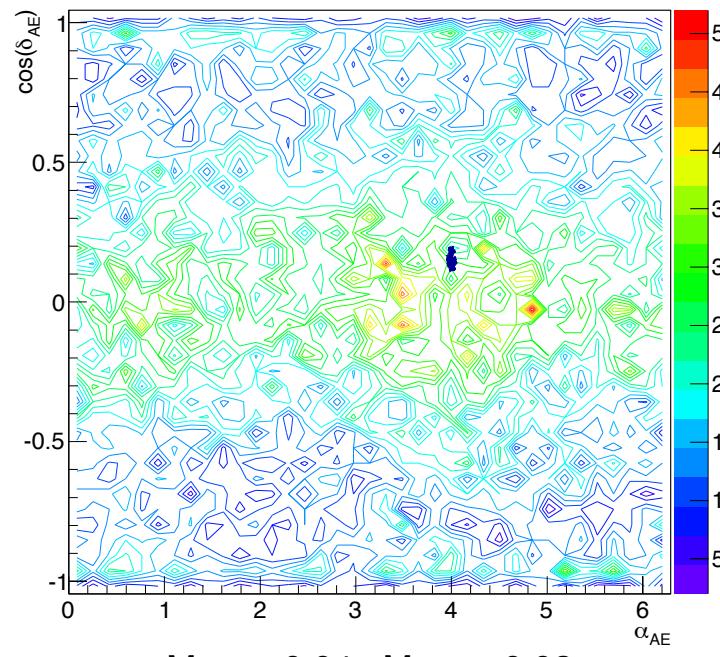
- Stellar disk plane: plane
- Two angles denotes directions of Angular momentum
  - : in plane
  - : from to
- Two pairs of for ESs & MBHs
  - Before ejection
  - After ejection



# Ejecting star angular momentum angle distribution

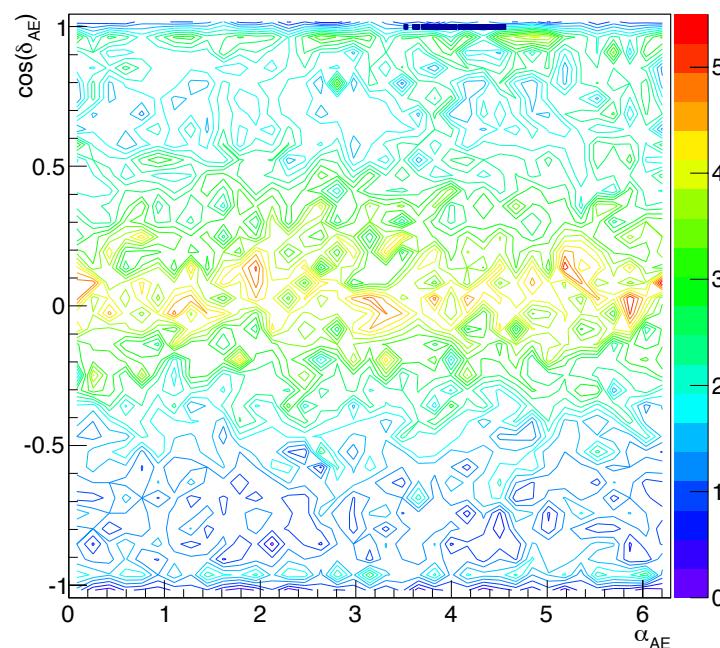
after ejection

$$M_{BH1} = 0.02, M_{BH2} = 0.02$$

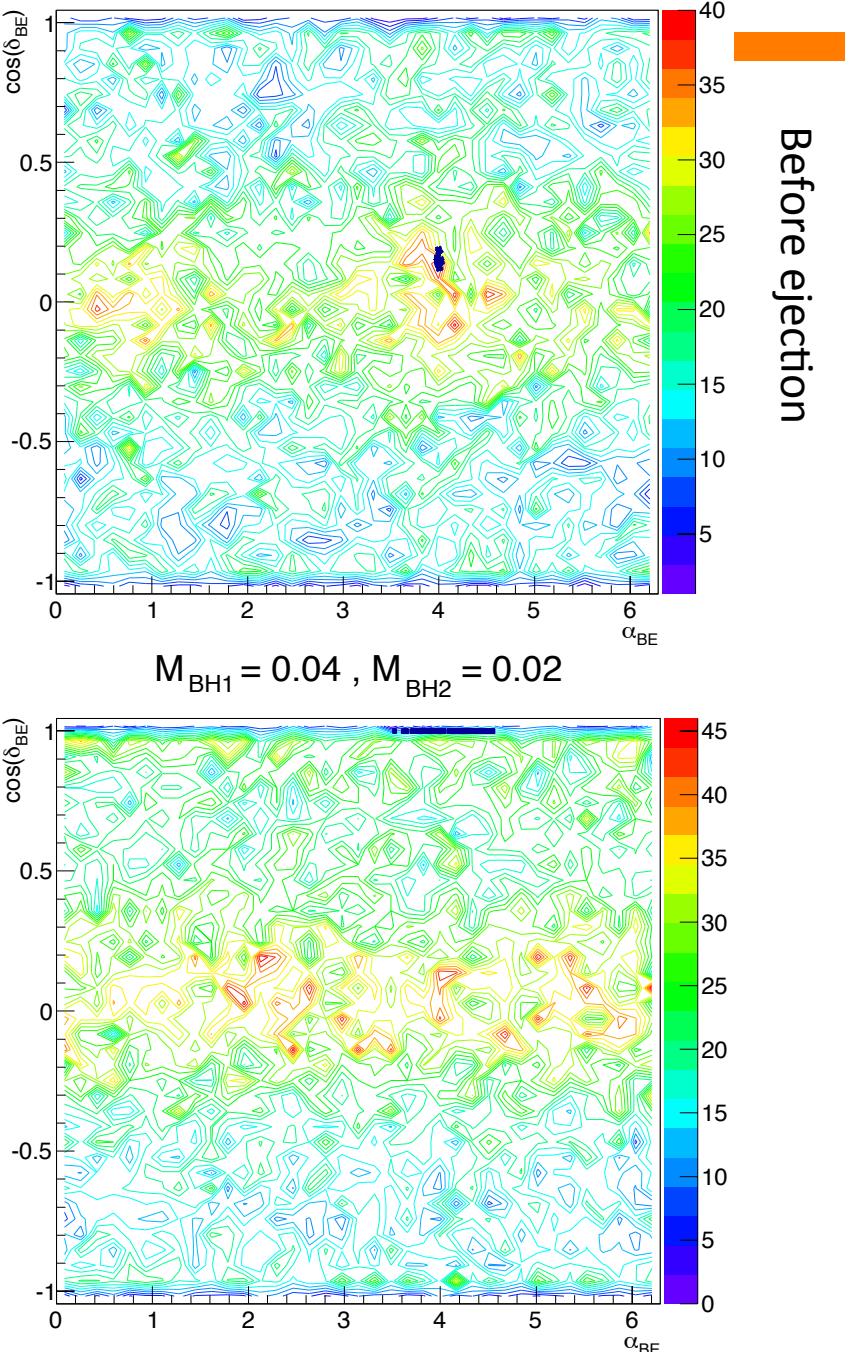


Before ejection

$$M_{BH1} = 0.04, M_{BH2} = 0.02$$

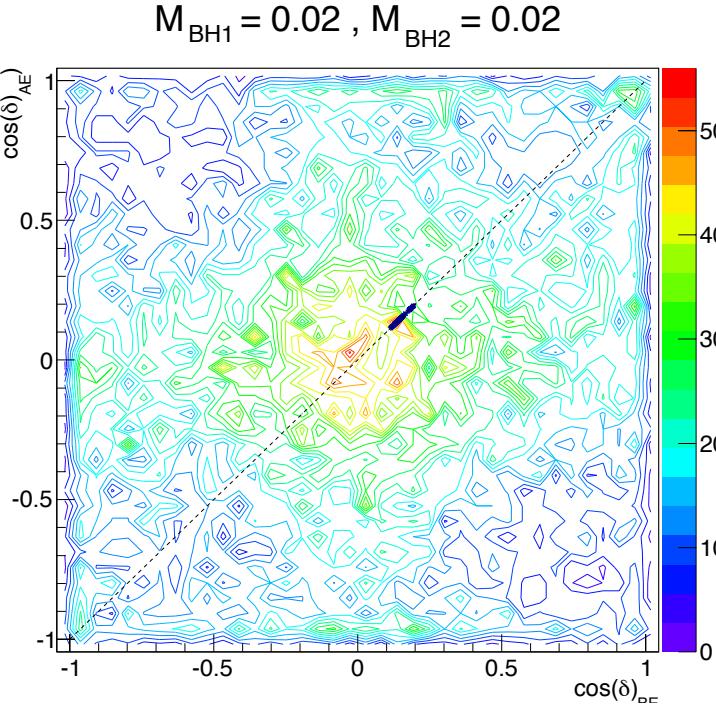
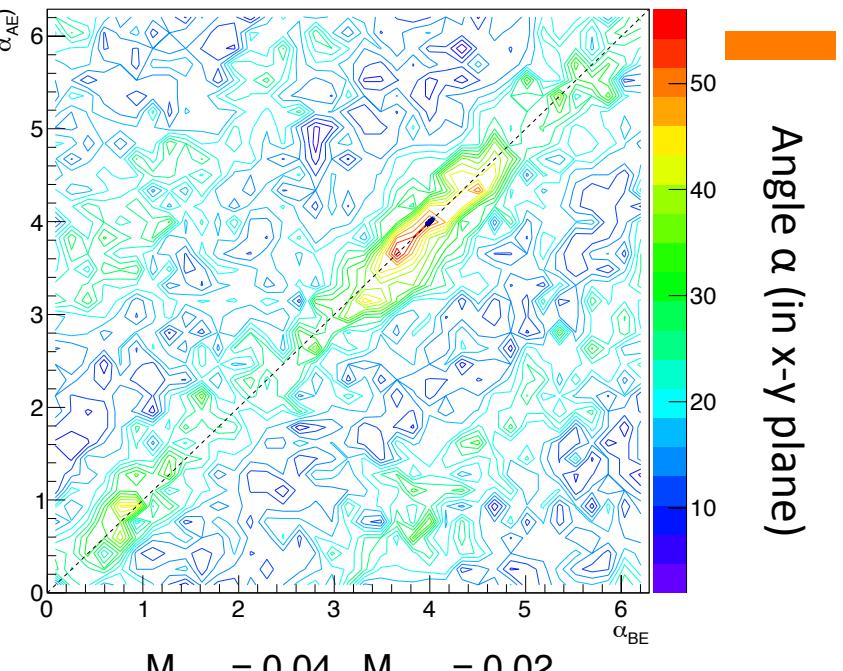


$$M_{BH1} = 0.04, M_{BH2} = 0.02$$

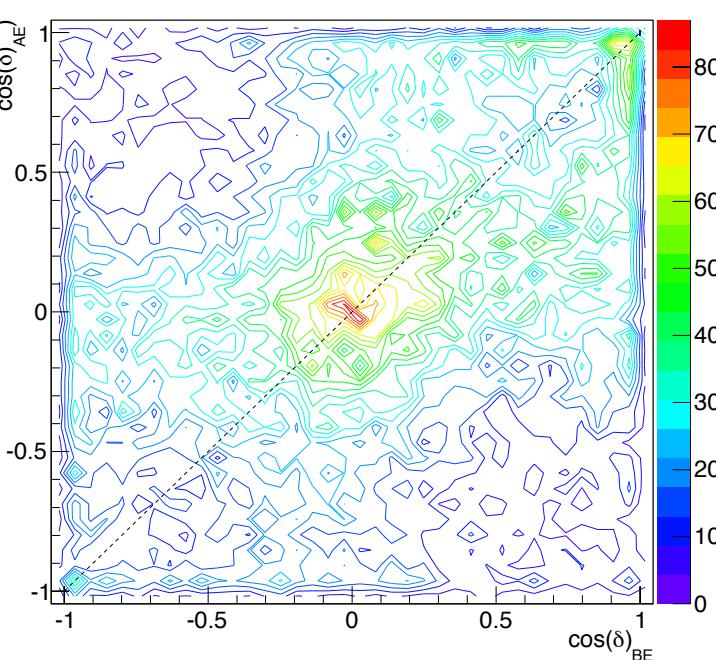
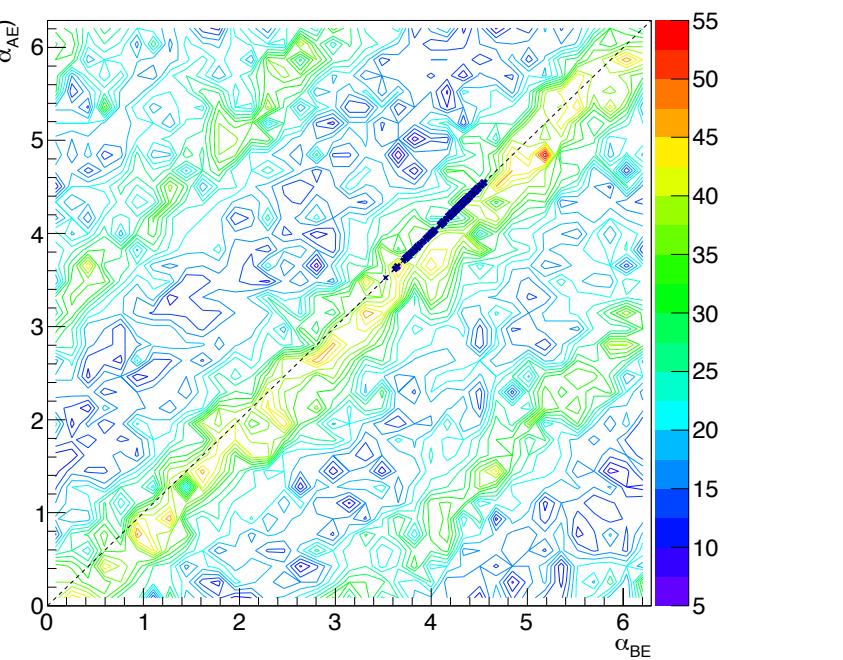


# Ejecting star angular momentum angle distribution

Angle  $\alpha$  (in x-y plane)

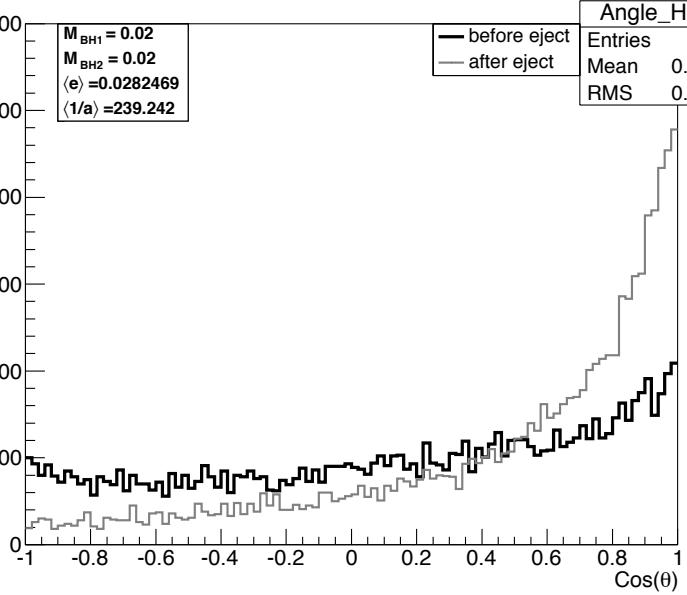


Angle  $\delta$  (from z to x-y plane)

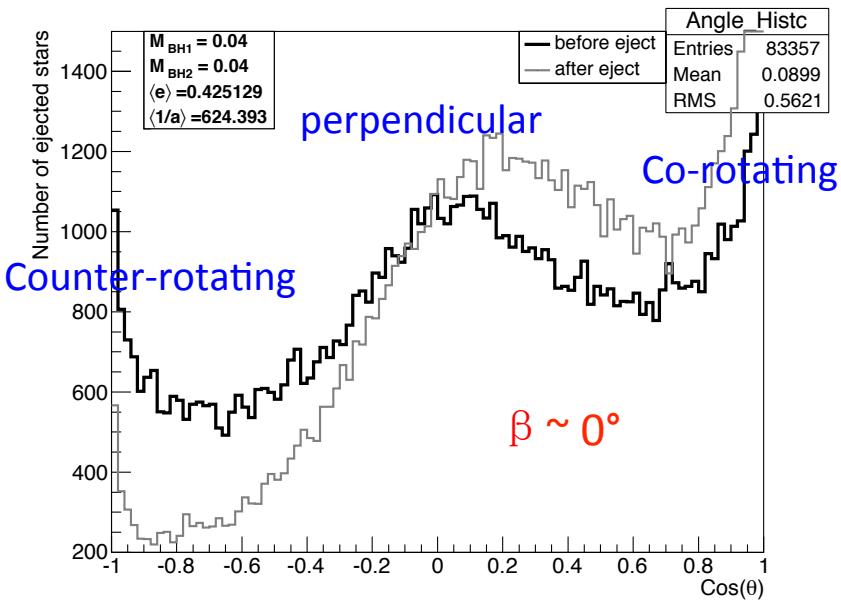
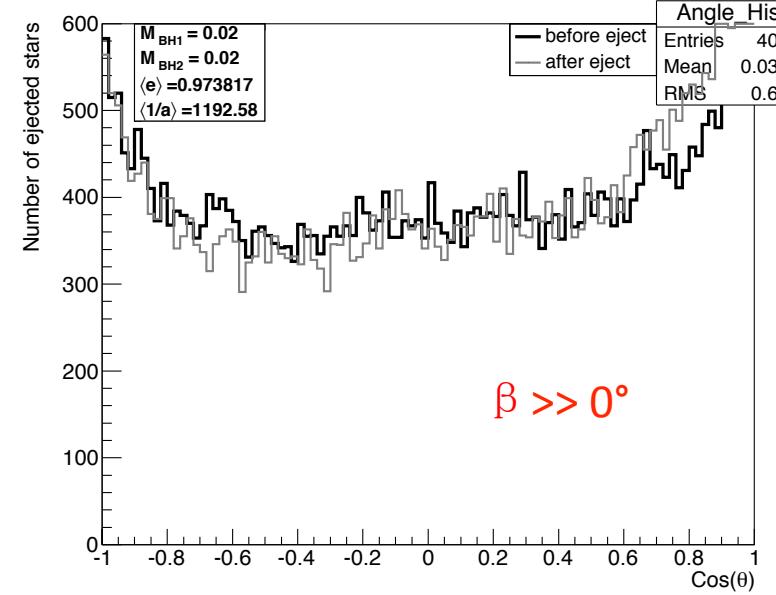


# Ejecting star angular momentum angle distribution

## Non-rotating models



## Rotating models



# Conclusion

- ↗ 0.08% - 8% of stars are ejected by MBHBs in 1M N-body simulations with 150 N-body time unit (~2Gyr).
- ↗ Eccentricity of MBHB grows in a stochastic way, where positive and negative K occur all the time, but there is an average trend towards higher eccentricity.
- ↗ In rotating model:
  - ↗ The angular momentum of ejected stars tend to whether increase or decrease after interaction.
  - ↗ the ejected stars tend to have co/counter-rotating orbit with MBHB or perpendicular orbit to stellar system.
- ↗ In non-rotating model
  - ↗ The angular momentum of ejected stars tend to be constant after interaction.
  - ↗ there is only the trend that ejected stars prefer co-rotating orbit with MBHB.
- ↗ MBHBs tend to switch stars with counter-rotating orbits into co-rotating orbits during their interactions.



# Star cluster simulations with Nbody6++ & GPU

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# Star cluster dynamics

Observations (Simon F. 2010)

Cluster	Age	M	R <sub>vir</sub>	ρ <sub>c</sub>	Z	Location	t <sub>dyn</sub>	t <sub>rh</sub>
Unit	Gyr	M <sub>⊙</sub>	pc	M <sub>⊙</sub> /pc <sup>3</sup>	Z <sub>⊙</sub>		Myr	Myr
OC	≤ 0.3	≤ 10 <sup>3</sup>	1	≤ 10 <sup>3</sup>	~ 1	disk	~1	≤ 100
GC	≥ 10	≥ 10 <sup>5</sup>	10	≥ 10 <sup>3</sup>	< 1	halo	≥ 1	≥ 1000
YMC	≤ 0.1	≥ 10 <sup>4</sup>	1	≥ 10 <sup>3</sup>	≥ 1	Galaxy	≤ 1	≤ 100

$$t_{dyn} = \left( \frac{GM}{r_{vir}^3} \right)^{-1/2} t_{rh} = 0.138 \frac{N^{1/2} r_h^{3/2}}{\langle m \rangle^{1/2} G^{1/2} \ln \Lambda}$$

Λ ~ 0.11N for equal mass system  
Λ smaller for large mass range  
(Spitzer, 1987)

Galaxies: collisionless system;

Star cluster: collisional system

# Star cluster dynamics

## Star cluster

Galaxy formation

Star formation

Massive star/  
Compact objects

Distance  
measurement

## Observations (Simon F. 2010)

Cluster	Age	M	R <sub>vir</sub>	ρ <sub>c</sub>	Z	Location	t <sub>dyn</sub>	t <sub>rh</sub>
Unit	Gyr	M <sub>⊙</sub>	pc	M <sub>⊙</sub> /pc <sup>3</sup>	Z <sub>⊙</sub>		Myr	Myr
OC	≤ 0.3	≤ 10 <sup>3</sup>	1	≤ 10 <sup>3</sup>	~ 1	disk	~1	≤ 100
GC	≥ 10	≥ 10 <sup>5</sup>	10	≥ 10 <sup>3</sup>	< 1	halo	≥ 1	≥ 1000
YMC	≤ 0.1	≥ 10 <sup>4</sup>	1	≥ 10 <sup>3</sup>	≥ 1	Galaxy	≤ 1	≤ 100

↗ Numerical simulation need to consider encounter and primordial binary effects

# Encounters & Binaries

Binney & Tremaine 2008

- ↗ Relaxation: loss memory
- ↗ Equipartition: mass segregation
- ↗ Escape: disruption of clusters
- ↗ Inelastic encounters: massive stars (Blue stragglers) formation
- ↗ Triple encounters: binary formation
- ↗ Interactions with primordial binaries: high binding energy of binaries transform to energy of cluster

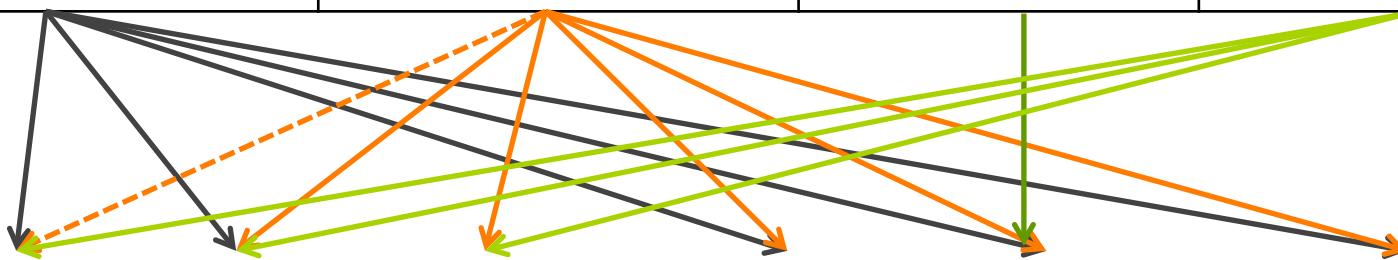
# Numerical methods

	<b>Fluid Dynamics</b>	<b>Monte Carlo/Fokker-Planck</b>	<b>Direct N-body</b>
Advantages	Easy to use methods from fluid dynamics	<ol style="list-style-type: none"><li>1. Very Fast</li><li>2. Include encounter effects</li></ol>	<ol style="list-style-type: none"><li>1. Very accurate</li><li>2. No assumption of dynamical process</li><li>3. All dynamical information</li></ol>
Disadvantages	Ignore the free path difference	<ol style="list-style-type: none"><li>1. Assume spherical symmetry</li><li>2. Assume velocity distribution for perturbations</li><li>3. Cannot resolve individual objects</li></ol>	

# N-body Method

## Direct N-body Method

Open Clusters/ GCs	GCs/Galactic nuclei	Open Clusters	Galactic nuclei
Nbody6/7	Nbody6++	Starlab	$\varphi$ GPU

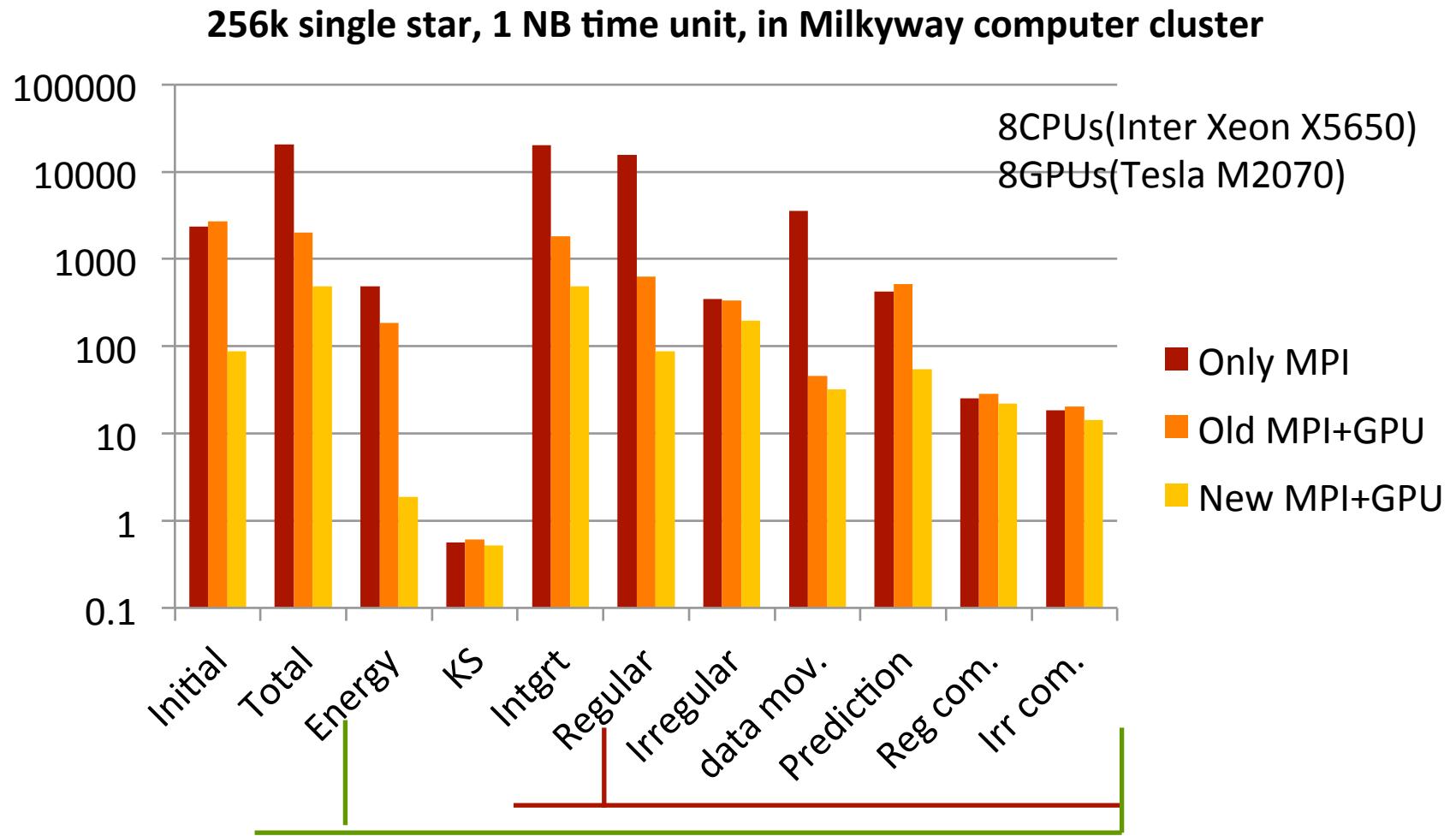


Parallel Inside node	GPU parallel	Parallel between nodes	Neighbor scheme	Kustaanheimo–Stiefel Method (KS)	Chain
OpenMP AVX/SSE2	Fast force calculation	MPI	Less force calculation	Accurate close encounter/binary calculation	Accurate dense multi-body calculation

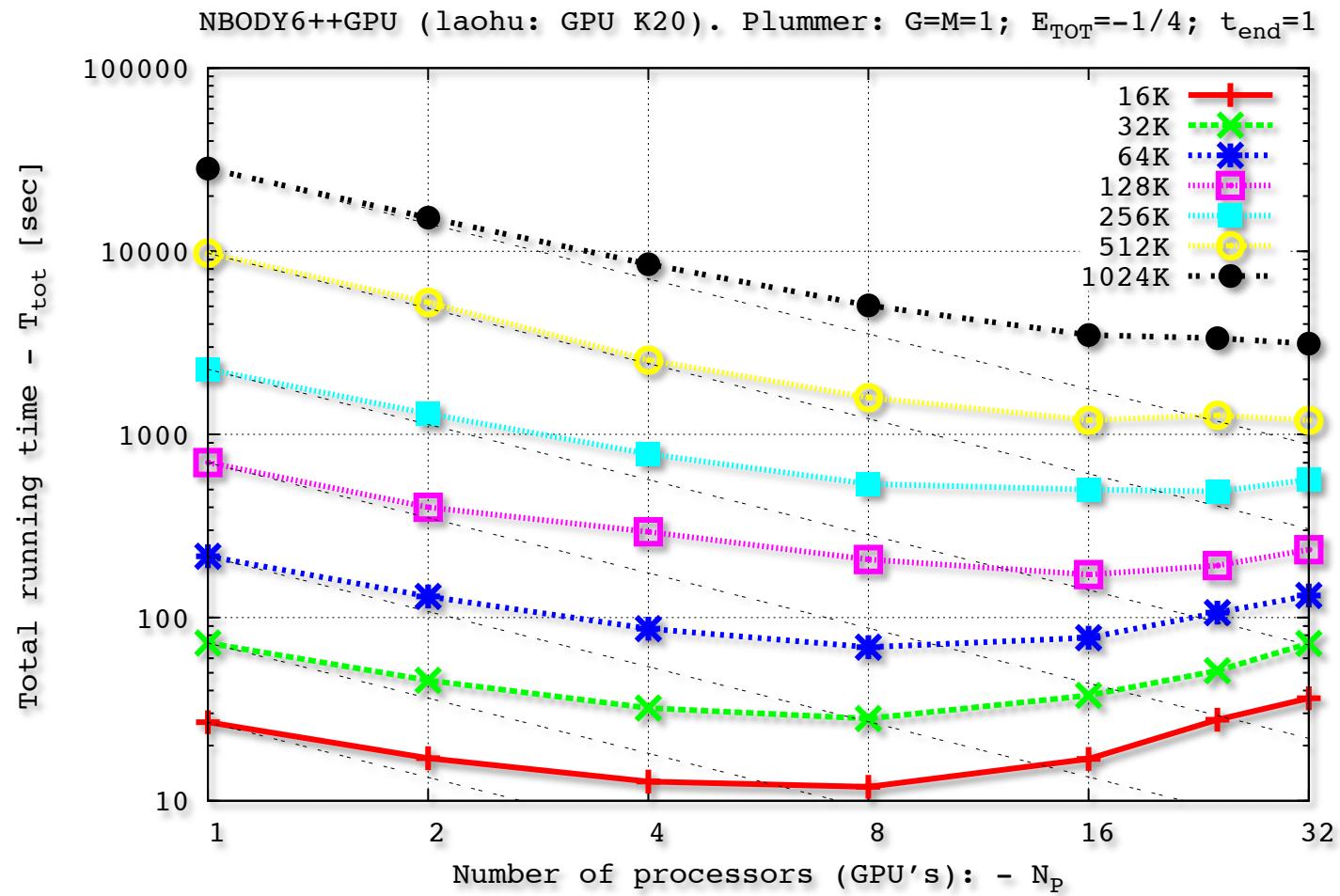
# Speed challenge

- ↗ Time requirement for Long-term 1M particle simulation
  - ↗ Typical scale factor ( $G=M=1$ ,  $E=-0.25$ )
    - ↗ Plummer model,  $R_{\text{vir}}=1\text{pc}$
    - ↗ Salpeter IMF  $a=2.3$ ,  $M_{\text{max}}=10M_{\odot}$ ,  $M_{\text{min}}=0.1M_{\odot}$
    - ↗  $1\text{Myr} \sim 50$  N-body time unit
  - ↗ 10Gyr simulation within one Month:
    - ↗  $\langle T_{\text{1NB}} \rangle = 5\text{s}$

# Recent Improvements for MPI+GPU



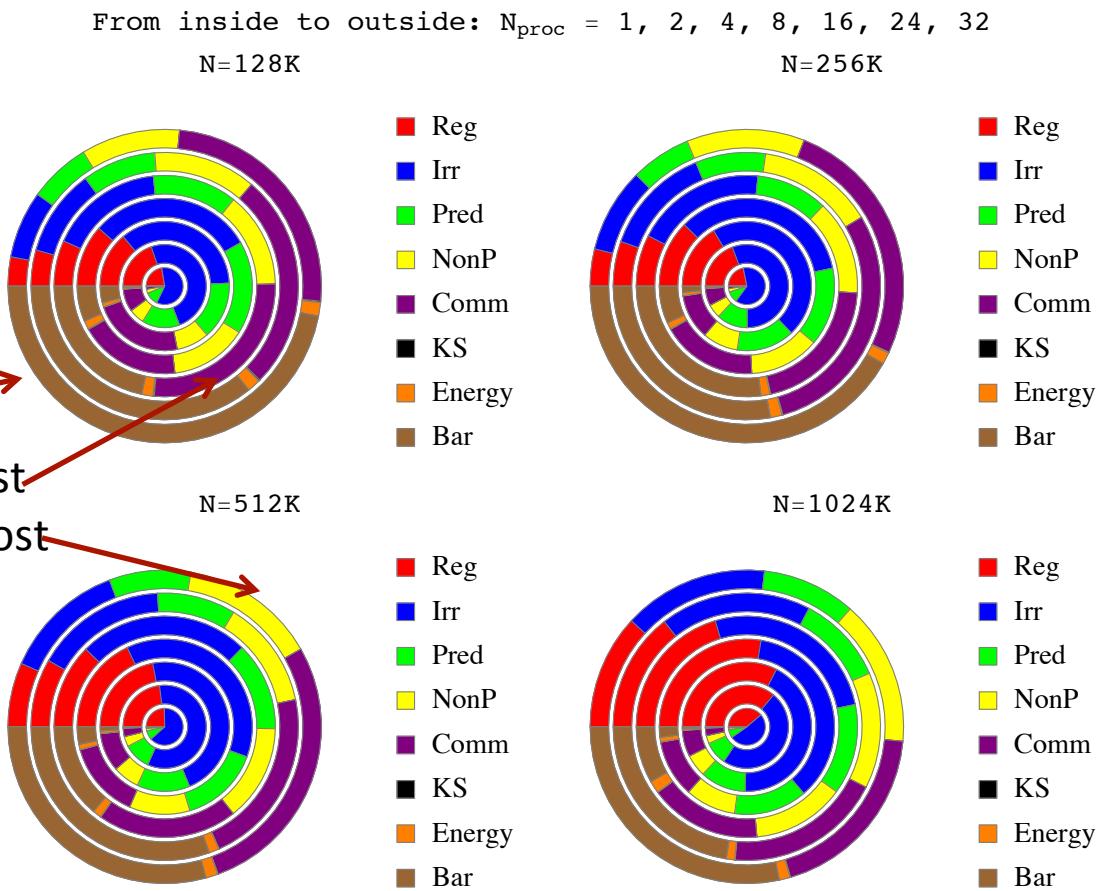
# Benchmark of NBODY6++



# Time fraction

- Very fast GPU part
- CPU dominated

1. Imbalance
2. Communication cost
3. Non-parallel part cost



# Strong mass loss by tidal field

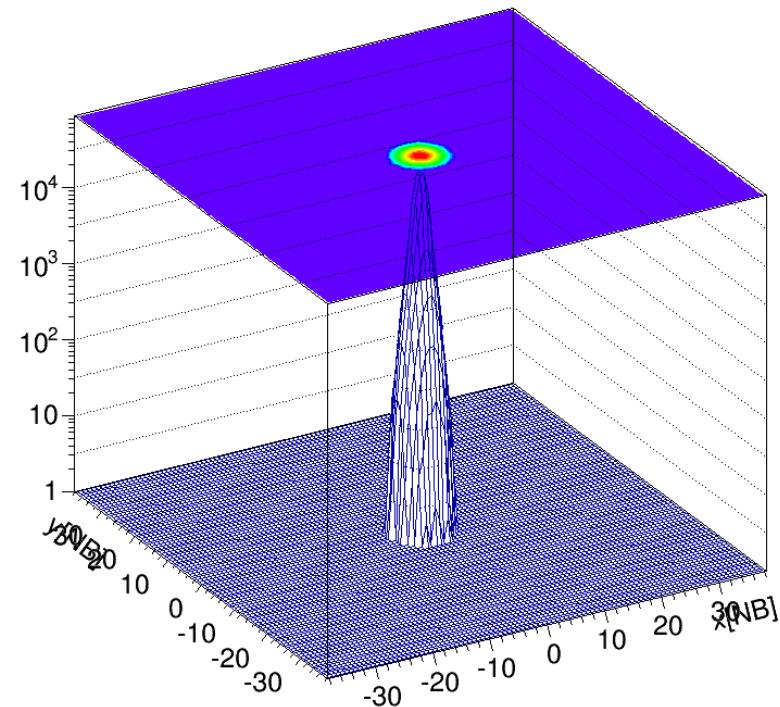
$N = 10^6$

$M = 574000.0 M_{\odot}$

$R_{\text{vir}} = 30.67 \text{ pc}$

Solar neighbor tidal field

Density  $T = 0 \text{ Myr}$



# Summary

- ↗ Direct N-body simulations are important for accurately understanding the dynamical evolution of star clusters.
- ↗ The speed of direct N-body simulation is still a big challenge for long-term evolution of massive star clusters.
- ↗ Nbody6++ speed up a lot recently
- ↗ KS parallelization will be done in the future